

UNIVERSIDAD POLITÉCNICA **DE MADRID**

Acceleration of data-driven modal decomposition using

unsupervised machine learning techniques

Jesús Garicano-Mena Dpto. Matemática Aplicada - ETSI Aeronáutica y del Espacio (UPM) Center for Computational Simulation

- 1) Describe classical Dynamic Mode Decomposition (DMD)
- 2) DMD as one of many data-driven modal decomposition techniques
- 3) DMD as a matrix factorization technique
- 4) Accelerating DMD methods
- 1) Describe classical Dynamic Mode Decomposition (DMD)
- 2) DMD as one of many data-driven modal decomposition techniques
- 3) DMD as a matrix factorization technique
- 4) Accelerating DMD methods

- B. Begiashvili *et al.,* Data-driven modal decomposition methods as feature detection techniques for flow problems: a critical assessment, Phys. Fluids 35, 041301 (2023).
- Li, et al., Dynamic Mode Decomposition Analysis of Spatially Agglomerated Flow Databases, Energies, vol. 13 (9), 2020.

N. Groun B. Li

S. Le Clainche

B. Begiashvili **E. Valero** E. Valero **J. Garicano Mena**

B. Begiashvili *et al.,* Data-driven modal decomposition methods as feature detection techniques for flow problems: a critical assessment, Phys. Fluids 35, 041301 (2023).

Li, et al., Dynamic Mode Decomposition Analysis of Spatially Agglomerated Flow Databases, Energies, vol. 13 (9), 2020.

Alleviating the computational cost

Conclusions

Introduction:

data-driven modal decomposition techniques

Credit: Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton, Kutz, *et al.*)

Credit: Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton, Kutz, *et al.*)

Matrix factorization techniques

Matrix factorization techniques

Dynamic Mode Decomposition
Temporal data sequence acquired at a fixed sampling frequency $1/\Delta t$

Arrange data in a (typically) tall and skinny matrix

Dynamic Mode Decomposition
Temporal data sequence acquired at a fixed sampling frequency $1/\Delta t$

Arrange data in a (typically) tall and skinny matrix

Dynamic Mode Decomposition
Temporal data sequence acquired at a fixed sampling frequency $1/\Delta t$

Arrange data in a (typically) tall and skinny matrix

From the complete data set

$$
\mathbf{V}_1^{n_t} = [\mathbf{v}_1, \, \mathbf{v}_2, \, \ldots, \, \mathbf{v}_{n_t-1}, \, \mathbf{v}_{n_t}] \in \mathbb{R}^{n_p \times n_t}
$$

Identify data subsequences as:

$$
\mathbf{V}_1^{n_t-1} = [\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{n_t-1}] \equiv \mathbf{X} \quad \text{and} \quad \mathbf{V}_2^{n_t} = [\mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_{n_t-1}, \mathbf{v}_{n_t}] \equiv \mathbf{Y}
$$

From the complete data set

$$
\mathbf{V}_1^{n_t} = [\mathbf{v}_1, \, \mathbf{v}_2, \, \ldots, \, \mathbf{v}_{n_t-1}, \, \mathbf{v}_{n_t}] \in \mathbb{R}^{n_p \times n_t}
$$

Identify data subsequences as:

$$
\mathbf{V}_1^{n_t-1} = [\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_{n_t-1}] \equiv \mathbf{X} \quad \text{and} \quad \mathbf{V}_2^{n_t} = [\mathbf{v}_2, \mathbf{v}_3, \ldots, \mathbf{v}_{n_t-1}, \mathbf{v}_{n_t}] \equiv \mathbf{Y}
$$

Assume a linear relationship:

$$
\mathbf{v}(t_{k+1}) = A \mathbf{v}(t_k)
$$

From the complete data set

$$
\mathbf{V}_1^{n_t} = [\mathbf{v}_1, \, \mathbf{v}_2, \, \ldots, \, \mathbf{v}_{n_t-1}, \, \mathbf{v}_{n_t}] \in \mathbb{R}^{n_p \times n_t}
$$

Identify data subsequences as:

$$
\mathbf{V}_1^{n_t-1} = [\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_{n_t-1}] \equiv \mathbf{X} \quad \text{and} \quad \mathbf{V}_2^{n_t} = [\mathbf{v}_2, \mathbf{v}_3, \ldots, \mathbf{v}_{n_t-1}, \mathbf{v}_{n_t}] \equiv \mathbf{Y}
$$

Assume a linear relationship:

$$
\mathbf{v}(t_{k+1}) = A \mathbf{v}(t_k)
$$

Koopman assumption

From the complete data set

$$
\mathbf{V}_1^{n_t} = [\mathbf{v}_1, \, \mathbf{v}_2, \, \ldots, \, \mathbf{v}_{n_t-1}, \, \mathbf{v}_{n_t}] \in \mathbb{R}^{n_p \times n_t}
$$

Identify data subsequences as:

$$
\mathbf{V}_1^{n_t-1} = [\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_{n_t-1}] \equiv \mathbf{X} \quad \text{and} \quad \mathbf{V}_2^{n_t} = [\mathbf{v}_2, \mathbf{v}_3, \ldots, \mathbf{v}_{n_t-1}, \mathbf{v}_{n_t}] \equiv \mathbf{Y}
$$

Assume a linear relationship:

$$
\mathbf{V}_2^{n_t} = A \mathbf{V}_1^{n_t - 1}
$$

$$
A \in \mathbb{R}^{n_p \times n_p}
$$

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_{1}^{n_{t}-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_{0} \mathbf{S}_{0} \mathbf{R}_{0}^{T} = \sum_{j=1}^{r} s_{0,j} \mathbf{1}_{0,j} \cdot \mathbf{r}_{0,j}^{T}
$$

The columns of $\mathbf{L}_{0} \Rightarrow$ Left Singular Vectors

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_1^{n_t-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_0 \; \mathbf{S}_0 \; \mathbf{R}_0^T = \sum_{i=1}^r s_{0,j} \, \mathbf{l}_{0,j} \cdot \mathbf{r}_{0,j}^T
$$

The columns of $L_0 \Rightarrow$ Left Singular Vectors (some consider these as POD modes)

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_1^{n_t-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_0 \; \mathbf{S}_0 \; \mathbf{R}_0^T = \sum_{i=1}^r s_{0,j} \, \mathbf{l}_{0,j} \cdot \mathbf{r}_{0,j}^T
$$

The columns of $L_0 \Rightarrow$ Left Singular Vectors (some consider these as POD modes ... if the temporally averaged state is substracted)

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_1^{n_t-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_0 \; \mathbf{S}_0 \; \mathbf{R}_0^T = \sum_{i=1}^r s_{0,j} \, \mathbf{l}_{0,j} \cdot \mathbf{r}_{0,j}^T
$$

The columns of $L_0 \Rightarrow$ Left Singular Vectors

Project into the reduced Left Singular Vector (sub)space and manipulate $\mathbf{L}_0 \mathbf{Y} \mathbf{R}_0 \mathbf{S}_0^{-1} = \mathbf{L}_0^T \mathcal{A} \mathbf{L}_0 \equiv \widetilde{\mathcal{A}} \in \mathbb{R}^{r \times r}$

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_1^{n_t-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_0 \; \mathbf{S}_0 \; \mathbf{R}_0^T = \sum_{i=1}^r s_{0,j} \, \mathbf{l}_{0,j} \cdot \mathbf{r}_{0,j}^T
$$

The columns of $L_0 \Rightarrow$ Left Singular Vectors

Project into the reduced Left Singular Vector (sub)space and manipulate \mathbf{L}_0 Y \mathbf{R}_0 $\mathbf{S}_0^{-1} = \mathbf{L}_0^T A \mathbf{L}_0 \equiv \widetilde{A} \in \mathbb{R}^{r \times r}$

Assumption: $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_1^{n_t-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_0 \; \mathbf{S}_0 \; \mathbf{R}_0^T = \sum_{i=1}^r s_{0,j} \, \mathbf{l}_{0,j} \cdot \mathbf{r}_{0,j}^T
$$

The columns of $L_0 \Rightarrow$ Left Singular Vectors

Project into the reduced Left Singular Vector (sub)space and manipulate \mathbf{L}_0 Y \mathbf{R}_0 $\mathbf{S}_0^{-1} = \mathbf{L}_0^T A \mathbf{L}_0 \equiv \widetilde{A} \in \mathbb{R}^{r \times r}$

Assumption: $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A} ,

but $r \leq n_t \ll n_p$

How does one identify A ? Well, you don't need to.

$$
\mathbf{V}_1^{n_t-1} \equiv \mathbf{X} \stackrel{SVD}{=} \mathbf{L}_0 \mathbf{S}_0 \mathbf{R}_0^T = \sum_{i=1}^r s_{0,j} \mathbf{1}_{0,j} \cdot \mathbf{r}_{0,j}^T
$$

The columns of $L_0 \Rightarrow$ Left Singular Vectors

Project into the reduced Left Singular Vector (sub)space and manipulate \mathbf{L}_0 Y \mathbf{R}_0 $\mathbf{S}_0^{-1} = \mathbf{L}_0^T A \mathbf{L}_0 \equiv \widetilde{A} \in \mathbb{R}^{r \times r}$

Assumption: $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A} ,

but $r \leq n_t \ll n_p$

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition

$$
\widetilde{\mathcal{A}} \mathbf{w}_j = \mathbf{w}_j \ \mu_j
$$

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition

$$
\widetilde{\mathcal{A}}\ \mathbf{W} = \mathbf{W}\ \mathbf{D}_{\mu}
$$

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition

 $\widetilde{\mathcal{A}} \mathbf{W} = \mathbf{W} \mathbf{D}_{\mu}$

Dynamic Modes are obtained projecting back into the LSV space

 $\mathbf{\Phi} = \mathbf{L}_0 \mathbf{W}$

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition $\widetilde{\mathcal{A}} \mathbf{W} = \mathbf{W} \mathbf{D}_{\mu}$

Dynamic Modes are obtained projecting back into the LSV space

 $\mathbf{\Phi} = \mathbf{L}_0 \mathbf{W}$

Temporal interpolation/extrapolation is possible:

$$
\mathbf{v}(\mathbf{r},t) = \sum_{j=1}^{r} \alpha_j \, \Phi_j \, e^{\lambda_j \, t} \qquad \qquad \text{where} \ \lambda_j = \frac{\log(\mu_j)}{\Delta \, t}
$$
\n's are known.

... once the α_i 's are known.

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition $\widetilde{\mathcal{A}} \mathbf{W} = \mathbf{W} \mathbf{D}_{\mu}$

Dynamic Modes are obtained projecting back into the LSV space

 $\Phi = \mathbf{L}_0 \mathbf{W}$

Temporal interpolation/extrapolation is possible:

$$
\mathbf{v}(\mathbf{r},t) = \sum_{j=1}^{r} \alpha_j \, \Phi_j \, e^{\lambda_j \, t} = \Phi \, \mathbf{D}_{\alpha} \, \mathbf{V}_{\lambda} \text{ where } \lambda_j = \frac{\log(\mu_j)}{\Delta \, t}
$$
\n's are known.

... once the α_i 's are known.

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition $\widetilde{\mathcal{A}} \mathbf{W} = \mathbf{W} \mathbf{D}_{\mu}$

Dynamic Modes are obtained projecting back into the LSV space

 $\mathbf{\Phi} = \mathbf{L}_0 \mathbf{W}$

Temporal interpolation/extrapolation is possible:

$$
\mathbf{v}(\mathbf{r},t) = \sum_{j=1}^{r} \alpha_j \, \Phi_j \, e^{\lambda_j t} = \Phi \, \mathbf{D}_{\alpha} \, \mathbf{V}_{\lambda} \text{ where } \lambda_j = \frac{\log(\mu_j)}{\Delta \, t}
$$
\n's are known.

... once the α_i 's are known.

Assumption $\tilde{\mathcal{A}}$ conveys most of the information codified in \mathcal{A}

Dynamic modes and Ritz values are obtained via eigendecomposition

 $\widetilde{\mathcal{A}} \mathbf{W} = \mathbf{W} \mathbf{D}_u$

Dynamic Modes are obtained projecting back into the LSV space

 $\Phi = \mathbf{L}_0 \mathbf{W}$

Temporal interpolation/extrapolation is possible:

$$
\mathbf{v}(\mathbf{r},t) = \sum_{j=1}^{r} \alpha_j \, \Phi_j \, e^{\lambda_j t} = \Phi \, \mathbf{D}_{\alpha} \, \mathbf{V}_{\lambda} \text{ where } \lambda_j = \frac{\log(\mu_j)}{\Delta \, t}
$$
\n's are known.

once the α_i 's are known.

An example

Credit: Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton, Kutz, *et al.*)

Credit: Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton & Kutz)

Credit: Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton & Kutz)
Dynamic Mode Decomposition

Synthesis (Reconstruction)

Credit: Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton & Kutz)

"Gentle" problem.

 $\mathcal{S}t$

Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton, Kutz, *et al.*)

M.R. Jovanovic, P.J. Schmid, J.W. Nichols, Sparsity-promoting dynamic mode decomposition, Phys. Fluids, vol. 26 (2), 2014.

Dynamic Mode Decomposition: Data-Driven Modeling of Complex Systems (Brunton, Kutz, *et al.*)

M.R. Jovanovic, P.J. Schmid, J.W. Nichols, Sparsity-promoting dynamic mode decomposition, Phys. Fluids, vol. 26 (2), 2014.

Dynamic Mode Decomposition can be understood both

- as a data-driven modal decomposition technique, and
- as matrix factorization technique

Dynamic Mode Decomposition can be understood both

- as a data-driven modal decomposition technique, and
- as matrix factorization technique

This leads to connections with other decomposition techniques:

FFT, Spectral POD, multi-scale POD, multi-resolution DMD ...

B. Begiashvili *et al.,* Data-driven modal decomposition methods as feature detection techniques for flow problems: a critical assessment, Phys. Fluids 35, 041301 (2023).

Matrix factorization techniques

Matrix factorization techniques

Matrix factorization techniques

SVD/DMD are both matrix factorization techniques

Matrix R_0 : Right Singular Vectors (time, real, mixes frequencies), R_0 ^H R_0 = I_n

SVD/DMD are both matrix factorization techniques

Matrix M_µ: Vandermonde matrix (time, complex, distinct frequencies)

SVD/DMD are both matrix factorization techniques

Alleviating the computational cost

There are many (n_p) spatial points in the system;

most of them will have coherent temporal variations.

There are many (n_p) spatial points in the system;

most of them will have coherent temporal variations.

Can few data points be representative of the whole database temporal behaviour?

There are (n_p) many spatial points in the system;

most of them will have coherent temporal variations.

Can few data points be representative of the whole database temporal behaviour?

Yes!

Those representative data points can be identified using *clustering* algorithms (Unsupervised Machine Learning).

ഗ

ത ce

Time

Guéniat, Mathelin & Pastur, Phys. Fluids, vol. 27 (2), 2015. Li, Garicano-Mena, Zheng & Valero, Energies, vol. 13 (9), 2020.

ഗ $\bf \Omega$ ത ce

Time

Guéniat, Mathelin & Pastur, Phys. Fluids, vol. 27 (2), 2015. Li, Garicano-Mena, Zheng & Valero, Energies, vol. 13 (9), 2020.

Guéniat, Mathelin & Pastur, Phys. Fluids, vol. 27 (2), 2015. Li, Garicano-Mena, Zheng & Valero, Energies, vol. 13 (9), 2020. How can one identify those modes that have a most representative temporal variation?

Group those points that have comparable pdf's.

How can one identify those modes that have a most representative temporal variation?

Group those points that have comparable pdf's.

It is not easy to identify a pdf from discrete data, though.

How can one identify those modes that have a most representative temporal variation?

Group those points that have comparable pdf's.

It is not easy to identify a pdf from discrete data, though.

Take N_m statistical moments as representative of the pdf.

Spatially Agglomerated DMD analysis

1. Compute the first \widetilde{N}_M (estimated) statistical moments, with $1 \leq \widetilde{N}_M \ll n_t$

2. Arrange those moments into matrix $\mathbf{\bar{M}} \in \mathbb{R}^{n_p \times \tilde{N}_M}$

- 3. Spatial Agglomeration feed $\mathbf M$ to clustering algorithm retrieve reduced database
- 4. Perform DMD analysis on spatially reduced database retrieve Ritz values & DMD modes
- 5. Reconstruct original DMD modes

Li, Garicano-Mena, Zheng & Valero, Dynamic Mode Decomposition Analysis of Spatially Agglomerated Flow Databases, Energies, vol. 13 (9), 2020.

the limit cycle.

 $Re_D = 60$ cylinder flow: C_l vs time and associated FFT spectrum.

DMD spectrum (Ritz values)

 $Re_D = 60$ cylinder flow: most relevant DMD modes, and corresponding frequencies and growth rates.

$$
\mathbf{F}=\left[f_0,f_1,f_2,f_3\right]
$$

$$
\boldsymbol{\Sigma} = \left[\sigma_0, \sigma_1, \sigma_2, \sigma_3\right]
$$

$$
\varepsilon_f = \frac{\left\|\mathbf{F} - \mathbf{F}_C\right\|_2}{\left\|\mathbf{F}_C\right\|_2}
$$

$$
\epsilon_\sigma = \frac{\|\boldsymbol{\Sigma}\|_2}{4}
$$

 $Re_D = 60$ cylinder flow: Normalized errors ε_f (Eq. (12)) and ε_σ (Eq. (13)) committed on capturing the top 4 frequencies f_i and corresponding growth rate σ_i with different clustering algorithms over spatial reduction $\widetilde{n_p}/n_p < 1$.

 $Re_D = 60$ cylinder flow: time invested (in seconds), for different clustering algorithms (averaged over 10 realizations).
Database: $Re_D=60$ flow around a cylinder

(a) K-means,
$$
\widetilde{n_p}/n_p = 0.1\%
$$
 ($\varepsilon_f = 4.26 \times$
\n(b) DBSCAN, $\widetilde{n_p}/n_p = 0.1\%$ ($\varepsilon_f = 10^{-3}, \varepsilon_\sigma = 4.23 \times 10^{-3}$).
\n(b) DBSCAN, $\widetilde{n_p}/n_p = 0.1\%$ ($\varepsilon_f = 10^{-3}, \varepsilon_\sigma = 4.23 \times 10^{-3}$).

 $Re_D = 60$ cylinder flow: The distribution of centroids/cores from different clustering algorithms, with spatial reduction $\widetilde{n_p}/n_p < 0.4\%.$

Database: $Re_D=60$ flow around a cylinder

(c) Gaussian Mixture, $\widetilde{n_p}/n_p = 0.4\%$ ($\varepsilon_f =$ 4.20×10^{-3} , $\varepsilon_{\sigma} = 5.02 \times 10^{-3}$)

(d) Gaussian Mixture, $\widetilde{n_p}/n_p = 0.1\%$ ($\varepsilon_f =$ $0.55, \varepsilon_{\sigma} = 14.5$).

 $Re_D = 60$ cylinder flow: The distribution of centroids/cores from different clustering algorithms, with spatial reduction $\widetilde{n_p}/n_p < 0.4\%$.

Domain and system of reference for the channel flow problem. The domain is periodic along x and z directions; bulk flow is along x direction.

Domain and system of reference for the channel flow problem. The domain is periodic along x and z directions; bulk flow is along x direction.

Domain and system of reference for the channel flow problem. The domain is periodic along x and z directions; bulk flow is along x direction.

"Small" database

 Re_τ = 200 turbulent channel flow: distribution of centroids along y^+ for different agglomeration strategies.

Re_c≈3600 TCF Composite DMD

Re_c≈3600 TCF Composite DMD

Choose those modes that have largest α_i

and use

$$
\mathbf{v}(\vec{r},t) = \sum_{j=1}^{n_t-1} \alpha_j \Phi_j(\vec{r}) e^{\lambda_j t} \text{ with } \lambda_j = \frac{\log \mu_j}{\Delta t}
$$

Choose those modes that have largest α_i

and use
\n
$$
\mathbf{v}(\vec{r},t) = \sum_{j=1}^{P-1} \alpha_j \Phi_j(\vec{r}) e^{\lambda_j t} \text{ with } \lambda_j = \frac{\log \mu_j}{\Delta t}
$$

 $V = \Phi D_a M_{\mu}$

Re_c≈3600 TCF Composite DMD

Composite DMD
Temporal data sequence acquired at a fixed sampling frequency $1/\Delta t$ Arrange data in a (typically) tall and skinny matrix

P.J. Schmid, J. Fluid Mech., vol. 656, 2010

Composite DMD

Temporal data sequence acquired at a fixed sampling frequency $1/\Delta t$ Instantaneous data groups two (or more) different variables into single column vector $\mathbf{v}(t_k)$ Arrange data in a (typically) tall and skinny matrix

T. Sayadi et al., J. Fluid Mech., vol. 748, 2014

Composite DMD

Applies to fully developed turbulent channel

K. Fukagata, K. Iwamoto and N. Kasagai, Phys. Fluids vol. 14, 2002

Analysis on composed $C_f(t_k)$ & u'v'(r, t_k) fields

$$
\beta_i \equiv (\phi_i \cdot \mathbf{e}_{C_f}) \alpha_i
$$

$$
\langle u'v'\rangle^{DMD}(y)=\frac{1}{n_s\Delta t^s}\sum_{i=1}^{n_r}\alpha_i\langle\phi_i-(\phi_i\cdot\mathbf{e}_{C_f})\mathbf{e}_{C_f}\rangle\int_0^{n_s\Delta t^s}e^{\lambda_i t}dt.
$$

Garicano-Mena, Li, Ferrer & Valero, A composite dynamic mode decomposition analysis of turbulent channel flows, Phys. Fluids, vol. 31, 2019.

Re_c≈3600 TCF Composite DMD

Composite Parallel DMD

Standard channel DMD spectra obtained from analysis based on u'v' and composite C_f -u'v' snapshots: amplitudes $|\alpha_i|/|\alpha_{max}|$ and $|\beta_i|/|\beta_{max}|$ vs angular pulsation $\mathfrak{I}(\lambda_i)$.

Composite Parallel DMD

Standard channel DMD spectra obtained from analysis based on u'v' and composite C_f -u'v' snapshots: amplitudes $|\alpha_i|/|\alpha_{max}|$ and $|\beta_i|/|\beta_{max}|$ vs angular pulsation $\mathfrak{I}(\lambda_i)$.

Composite Parallel DMD

$$
Re_{\tau}
$$
 = 200 turbulent channel flow: **DMD** reconstruction of the field $-\frac{\langle u'v'\rangle}{u_{\tau}^2}(y^+, z^+)$

0.608 1 1.21/

 \mathbf{z}^*

$$
Re_{\tau}
$$
 = 200 turbulent channel flow: **DMD** reconstruction of the field $-\frac{\langle u'v'\rangle}{u_{\tau}^2}(y^+,z^+)$

Spatial Agglomeration & DMD

DMD analysis applied on Spatially Agglomerated Databases

allows effective reduction of computational costs

while retaining accurate results.

Spatial Agglomeration & DMD

DMD analysis applied on Spatially Agglomerated Databases

allows effective reduction of computational costs

while retaining accurate results.

Succesful example of combination of (Unsupervised) Machine Learning Algorithms & data-driven modal decomposition techniques.

Li, Garicano-Mena, Zheng & Valero, Dynamic Mode Decomposition Analysis of Spatially Agglomerated Flow Databases, Energies, vol. 13 (9), 2020.

Conclusions

Data-driven modal decomposition techniques \rightleftharpoons matrix factorization:

SVD is univoquely defined, but mixes frequencies.

DMD identifies distinct frequencies, but needs solving an optimization problem.

Data-driven modal decomposition techniques \rightleftharpoons matrix factorization:

SVD (POD) is univoquely defined, but mixes frequencies.

DMD identifies distinct frequencies, but needs solving an optimization problem. Fortunately, a closed solution is available.

Computational cost of data-driven modal decomposition analysis:

Potentially expensive & large memory footprint.

Computational cost of Data-driven modal decomposition analysis:

Potentially expensive & large memory footprint.

Strategies to alleviate the computational cost available:

- Spatial Agglomeration,
- Memory-distributed parallelism (not discussed today).

More sophisticated variants available:

Higher-Order SVD (tensor formulation): very robust against noise.

More sophisticated variants available:

```
Higher-Order SVD (tensor formulation):
very robust against noise.
```
Higher-Order DMD: uses a generalized, d-lagged Koopman assumption capable of unravel very complex dynamics.

$$
\mathbf{v}(t_{k+1}) = A \mathbf{v}(t_k)
$$

More sophisticated variants available:

```
Higher-Order SVD (tensor formulation):
very robust against noise.
```
Higher-Order DMD: uses a generalized, d-lagged Koopman assumption capable of unravel very complex dynamics.

$$
\begin{aligned}\n\mathbf{v}(t_{k+1}) &= \mathcal{A}\,\mathbf{v}(t_k) \\
\mathbf{v}(t_{k+d}) &= \mathcal{A}_1\,\mathbf{v}(t_k) + \mathcal{A}_2\,\mathbf{v}(t_{k+1})\,\ldots + \mathcal{A}_d\,\mathbf{v}(t_{k+d-1})\n\end{aligned}
$$

More sophisticated variants available:

Higher-Order SVD (tensor formulation): very robust against noise.

Higher-Order DMD: uses a generalized, d-lagged Koopman assumption capable of unravel very complex dynamics

Applications also beyond fluid dynamics, e.g. Medical Imaging (echocardiography videos, MRI data)

Groun, Le Clainche et al., Higher order dynamic mode decomposition: From fluid dynamics to heart disease analysis, Computers in Biology and Medicine, Vol 144, 2022. Groun, Le Clainche et al., A novel data-driven method for the analysis and reconstruction of cardiac cine MRI, Computers in Biology and Medicine, Vol. 151, 2022.

More sophisticated variants available:

Higher-Order SVD (tensor formulation): very robust against noise.

Higher-Order DMD: uses a generalized, d-lagged Koopman assumption capable of unravel very complex dynamics

Combinations with Neural Network technology.
Methodology (1999) Conclusions

More sophisticated variants available:

Higher-Order SVD (tensor formulation): very robust against noise.

Higher-Order DMD: uses a generalized, d-lagged Koopman assumption capable of unravel very complex dynamics.

Combination with Neural Network technology.

No restriction on data origin.

- 1) Describe classical Dynamic Mode Decomposition (DMD)
- 2) DMD as one of many data-driven modal decomposition techniques
- 3) DMD as a matrix factorization technique
- 4) Accelerating DMD methods

mendements Acknowledgements

- Grant TED2021-129774B-C21, funded by MCIN/AEI/10.13039/501100011033 and by the European Union "NextGenerationEU"/PRTR (DigitHEART)

- Grant PLEC2022-009235, funded by MCIN/AEI/10.13039/501100011033 (CardioAging) NextGenerationEU

Thank you for your attention

Questions?