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Data-driven modelling

• How to **identify flow models** from **data**?

• Flow behavior is typically complex, data are **hard to interpret** directly.

Divide and conquer strategy:

- model the flow as a superposition of simpler modes;
- understand the interaction between modes.



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Proper Orthogonal Decomposition

 $\boldsymbol{a}(\boldsymbol{x},t) = \sum_{i=1}^{i} \boldsymbol{\psi}^{(i)}(t) \, \boldsymbol{\sigma}^{(i)} \, \boldsymbol{\phi}^{(i)}(\boldsymbol{x})$

space

- In its most common implementation, POD separate variables in a vector field:
 - $\phi^{(i)}(x)$ are the spatial basis functions
 - $\psi^{(i)}(t)$ are the temporal basis function
 - $\left|\sigma^{(i)}\right|^2$ are representative of an "energy" (kinetic energy for a velocity field)



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POD in discrete space

• Snapshot method (Sirovich, 1987):

$$= a(\mathbf{x}, \mathbf{t}^{(1)})$$
$$= a(\mathbf{x}, \mathbf{t}^{(2)})$$

$$A = \begin{bmatrix} a(\mathbf{x}, \mathbf{t}^{(1)}) \\ a(\mathbf{x}, \mathbf{t}^{(2)}) \\ \vdots \\ a(\mathbf{x}, \mathbf{t}^{(n)}) \end{bmatrix}$$

$$=a(\mathbf{x},t^{(n)})$$

• Time correlation matrix:

$$R_{t} = AA^{T} = \Psi \Sigma \Sigma^{T} \Psi^{T}$$
$$\Psi = \begin{bmatrix} \psi^{(1)}(t^{(1)}) & \cdots & \psi^{(r)}(t^{(1)}) \\ \vdots & \ddots & \vdots \\ \psi^{(1)}(t^{(n_{t})}) & \cdots & \psi^{(r)}(t^{(n_{t})}) \end{bmatrix}$$

• Spatial correlation matrix:

$$R_{s} = A^{T}A = \Phi \Sigma^{T} \Sigma \Phi^{T}$$

$$\begin{bmatrix} \phi^{(1)}(\chi^{(1)}) & \cdots & \phi^{(r)}(\chi^{(1)}) \end{bmatrix}$$

$$\Phi = \begin{bmatrix} \varphi^{(r)}(\underline{x}^{(r)}) & \cdots & \varphi^{(r)}(\underline{x}^{(r)}) \\ \vdots & \ddots & \vdots \\ \phi^{(1)}(\underline{x}^{(n_p)}) & \cdots & \phi^{(r)}(\underline{x}^{(n_p)}) \end{bmatrix}$$

- Singular Value Decomposition (SVD): $A = \Psi \Sigma \Phi^{T}$



Unsteady forces on flapping wings





Rival et al. (2009), Exp Fluids

- Flapping wings are characterized by vortices over the wing due to flow separation.
- These vortices produces low pressures, resulting in high lift and propulsive forces.
- Existing data-driven force models cannot be easily interpreted.
- Is it possible to identify an interpretable datadriven model for the forces?
- Using a flow-based decomposition to identify the relation between vortices and forces on the wing.



Experimental setup

• Flapping kinematics: $h(t) = c \sin(2\pi f t)$ $\theta(t) = \theta_0 \sin\left(2\pi f t + \frac{\pi}{2}\right)$

$$St = \frac{2cf}{V_{\infty}} = 0.2$$
$$Re = \frac{\rho V_{\infty}c}{\mu} = 3600$$
$$k = \frac{\pi fc}{V_{\infty}} = 0.63$$
$$\theta_0 = 10^{\circ}$$

- Measurements:
 - 80 phase-averaged 2D-PIV velocity fields in the midspan section;
 - Time-resolved aerodynamic loads from the load-cell.



Changing the reference frame

- The fluid domain changes with time.
- POD does not directly account for time-varying domain.
- The reference frame has been re-centered on the wing to avoid changes in the domain boundaries.



Velocity Decomposition: results

• Mode 0 is the time average.

 $\phi^{(0)}(x)$

- It represent a flow parallel to the chord.
- Modes 1+2 are "sinusoidal" contributions in phase quadrature.
- They represent the circulation over the airfoil.

32.3% KE



Low-order model





$$\sum_{i=1}^{2} \psi^{(i)} \sigma^{(i)} \phi^{(i)} \approx \mathrm{e}^{-j\omega t} (\sigma^{(1)} \phi^{(1)} + j \, \sigma^{(2)} \phi^{(2)})$$



Low-order model







POD and Stochastic Estimation

 Linear Stochastic Estimation (LSE) given the multipoint signals a(x,t) and b(x,t), their linear relation X is given (stochastically) by

$$(A^T A) \mathbf{X} = B^T A \quad \Rightarrow \quad \mathbf{X} = (A^T A)^{-1} B^T A$$

$$A = \begin{bmatrix} a(\mathbf{x}_{a}, t^{(1)}) \\ \vdots \\ a(\mathbf{x}_{a}, t^{(n_{t})}) \end{bmatrix}$$
$$B = \begin{bmatrix} b(\mathbf{x}_{b}, t^{(1)}) \\ \vdots \\ b(\mathbf{x}_{b}, t^{(n_{t})}) \end{bmatrix}$$

• POD

$$A = \Psi_A \Sigma_A \Phi_A^T \quad \Rightarrow \quad \Psi_A = A \Phi_A \Sigma_A^{-1}$$

 POD-LSE (or Extented POD, Borée, 2003) the LSE of the temporal POD modes provides the stochastic linear relation

$$(\Psi_A^T \Psi_A) (\Sigma_B \Phi_B^T) = B^T \Psi_A \quad \Rightarrow \quad \Sigma_B \Phi_B^T = B^T \Psi_A$$



Flow Field / Force Model: results





* Theodorsen, T. (1935) NACA report 496 uc3m Universidad Carlos III de Madrid [†] Garrick, I.E. (1937) NACA report 567

Flow Field / Force Model: summary



space

- Using POD and LSE a model linking flow fields and forces is extracted from data*.
- The model is physically sound:
 - Modes 1 and 2 model wing circulation and reference frame rotation and provide circulatory force on y and added-mass force on x.
 - Higher order modes model wake shedding and provide suction force on x.
- The link is purely stochastic!
- Can we use a more deterministic approach?

Pressure computation



space

• Pressure and velocity are linked through the Poisson equation:

$$\nabla^2 p = -\rho \nabla \cdot (\boldsymbol{u} \cdot \nabla) \boldsymbol{u}$$

- Finite differences solver;
- Neumann boundary condition on the airfoil

$$\nabla p = -\rho \frac{D\boldsymbol{u}}{Dt} - \mu \nabla^2 \boldsymbol{u}$$

- Neumann and Dirichlet conditions on the external boundaries;
- velocity fields are interpolated on a finer mesh
 - 317×244 vect. $\rightarrow 634 \times 479$ vect.

Loads computation

• Loads are computed from the pressure over the airfoil surface:

$$\mathbf{F} = \oint p \, \mathbf{n} \, ds$$







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• Performing a **Galerkin projection** of the Poisson equation:

$$\nabla^{2} p = -\rho \nabla \cdot (\boldsymbol{u} \cdot \nabla) \boldsymbol{u} \\ \boldsymbol{u} = \sum_{i=0}^{n} \psi^{(i)} \sigma^{(i)} \boldsymbol{\phi}^{(i)}$$

$$\Rightarrow \nabla^{2} p(\boldsymbol{x}, t) = \sum_{i=0}^{n} \sum_{j=0}^{n} \psi^{(i)} \psi^{(j)} \sigma_{p}^{(i,j)} \nabla^{2} P^{(i,j)}$$

$$\begin{array}{c} \psi^{(i)} : & \text{Time Mode i} \\ \sigma^{(i)} : & \text{Singular Value i} \\ \boldsymbol{\phi}^{(i)} : & \text{Space Mode i} \\ p^{(i,j)} : & \text{Pressure} \\ & \text{contribution} \\ \text{of modes i and j} \end{array}$$

 The quadratic relation between velocity modes and pressure can be retrieved using the Quadratic Stochastic Estimation (QSE):

 $(\Upsilon^T \Upsilon) \mathbf{P} = p^T \Upsilon \Rightarrow \mathbf{P} = (\Upsilon^T \Upsilon)^{-1} p^T \Upsilon$

$$\Upsilon = \begin{bmatrix} \psi^{(0)}(t_1)\psi^{(0)}(t_1) & \cdots & \psi^{(0)}(t_1)\psi^{(n)}(t_1) & \cdots & \psi^{(n)}(t_1)\psi^{(n)}(t_1) \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ \psi^{(0)}(t_n)\psi^{(0)}(t_n) & \cdots & \psi^{(0)}(t_n)\psi^{(n)}(t_n) & \cdots & \psi^{(n)}(t_n)\psi^{(n)}(t_n) \end{bmatrix}$$

Velocity/Pressure Decomposition: results



space

- The QSE is performed on the first 3 POD modes: $p(\mathbf{x},t) \approx \sum_{i=0}^{3} \sum_{j=0}^{3} \psi^{(i)}(t)\psi^{(j)}(t)\sigma_{p}^{(i,j)}P^{(i,j)}(\mathbf{x})$ $F_{y}(t) \approx \sum_{i=0}^{3} \sum_{j=0}^{3} \psi^{(i)}(t)\psi^{(j)}(t)\sigma_{F_{y}}^{(i,j)}$ $F_{x}(t) \approx \sum_{i=0}^{3} \sum_{j=0}^{3} \psi^{(i)}(t)\psi^{(j)}(t)\sigma_{F_{x}}^{(i,j)}$ Most of the terms are relevant for the
- Most of the terms are relevant for the pressure field (σ_P).
- The normal force is mainly dominated by linear contributions $P^{(0,0)}$, $P^{(0,1)}$, $P^{(0,2)}$.
- The chordwise force is mainly dominated by $P^{(0,0)}$ and $P^{(1,2)}$.

- The contribution $P^{(0,0)}$ is constant in time: $\sigma_P^{(0,0)}P^{(0,0)}$
- Contribution of the chord-wise flow.
- Pressure acts mainly in the chord-wise direction.





- The contributions $P^{(0,1)}$ and $P^{(0,2)}$ are linear: $\psi^{(i)}(t)\sigma_P^{(0,i)}P^{(0,i)}$
- Interaction between the circulation (modes 1+2) and the chordwise flow in mode 0.



- This pressure is antisymmetric wrt the chord.
- It is associated mainly with chord-normal forces.



The contributions P^(1,1), P^(1,2) and P^(2,2) are quadratic:

 $\psi^{(i)}(t)\psi^{(j)}(t)\sigma_P^{(i,j)}P^{(i,j)}$

 Mutual interaction between the circulation (modes 1+2).



• It mainly contribute to chordwise force.



Reduced model: velocity and pressure fields



ler



Velocity/pressure decomposition: summary

- POD and QSE can provide a combined velocity/pressure decomposition of the flow features on the wing*.
- The main flow features are:
 - chord-wise mean flow;
 - time-evolving vortex over the wing.
- A more deterministic force/flow field model is obtained:
 - a constant chord-wise force contribution from the chord-wise mean;
 - a linear chord-normal force contribution arising from the interaction between the chordwise flow and the wing vortex
 - a quadratic chord-wise force contribution from the vortex.



Advecting wavepackets in subsonic jet noise

- Subsonic jet noise is dominated by sound emission from convective flow structures in the jet.
- These structures are referred to as wavepackets.
- These structures are:
 - coherent in the azimutal direction;
 - modulated in the axial direction;
 - temporally intermittent;
 - not highly energetic.







Crow & Champagne, JFM, 1971



Suzuki & Colonius, JFM, 2006

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Identification of wavepackets

- A large body of work is dedicated to *educe* wavepackets from jet flows.
- Wavepackets should be coherent in the spatio-temporal sense: $A(x,t)e^{j(kx-\omega t)}$
- SPOD (Towne et al., 2017) is generally used to detect and study wave-packets.
- The main drawback of SPOD is the need for time resolution.
- The successful application of this technique is mostly limited to LES data, limiting the number of studies in this subject.





Cavalieri et al., AMR, 2019

Aero space • A travelling wave in the complex domain is given by:

$$(a + jb)e^{-j\omega t} = \underbrace{(a\cos(\omega t) + b\sin(\omega t))}_{f(t)} + j\underbrace{(b\cos(\omega t) - a\sin(\omega t))}_{H[f(t)]_t}$$

• The Hilbert Transform H produce a $\pi/2$ shift of the signal:

$$H[f(t)]_t = \frac{1}{\pi} p. v. \int_{-\infty}^{+\infty} \frac{f(\tau)}{(t-\tau)} d\tau$$

• The complex-valued extension of f(t) is the Analytic Signal $\hat{f}(t)$

$$\hat{f}(t) = f(t) + j H[f(t)]_t = |f_A(t)| e^{j\theta(t)}$$





Hilbert POD

 Using the Analytic Signal (in time) and standard SVD, a complex extension of the POD* can be obtained:

$$\widehat{u}(x,t) = u(x,t) + jH[u(x,t)]_t = \sum_{i} \widehat{\psi}_i(t) \sigma_i \widehat{\phi}_i(x)$$

$$\underset{\text{Complex Time Mode Value Mode}}{\text{Complex Space Mode Node}}$$

- Time resolution is required!
- Is it possible to trade **space resolution** for **time resolution**?
- For travelling modes:

$$\sum_{i} |\hat{\psi}_{i}(t)| \sigma_{i} |\hat{\phi}_{i}(x)| e^{j(kx-\omega t)} = u(x,t) + jH[u(x,t)]_{x} = \hat{u}(x,t)$$
$$H[u(x,t)]_{x} = \frac{1}{\pi} p.v. \int_{-\infty}^{+\infty} \frac{u(\lambda,t)}{(x-\lambda)} d\lambda$$

• The Hilbert transform can be performed also in **space** *!



*Barnett, MWR, 1982; Kriegseis et al., ISPIV 2021 uc3m Universidad Carlos III de Madrid

*Raiola, SFMC, 2022

Turbulent Jet Dataset

- High Fidelity LES dataset (Towne et al, AIAA, 2023):
 - $M_{jet} = 0.9$
 - $Re_{jet} = \frac{U_{jet} d}{v} \approx 10^{6}$ $\Delta t = 0.2 \frac{d}{c_0}$

 - 10000 snapshots
 - $30d \times 6d$ in x-r plane
 - $656 \times 138 \times 128$ gridpoints
- Only the axisymmetric part is used, i.e. azimuthal wavenumber 0.
- Streamwise and radial velocity fields in a x-r plane.





HPOD results

Aero Space



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Oscillator model

space



The wavepacket behavior is better highlighted through an oscillator model:

 $\Phi(\mathbf{x})e^{-i\omega t}$

 The real temporal behavior is more complicated...

HPOD results

Aer σ

space



The real temporal behavior

Aer σ

space



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Wavepackets in jet flows: summary

- The **Hilbert POD** provides a complex-value extension of classic POD.
- A space-only implementation is obtained by switching from time to convective direction to provide the phase information of the wave.
- The space-only HPOD can extract wavepackets from turbulent jet flow fields without need of temporally resolved data.
- These wavepackets are not spectrally pure but live in a **time-frequency domain**.
- These velocity wavepackets can be used to decompose the Lighthill's analogy source term using a Galerkin projection...

... but this another story (for the AIAA/CEAS Aeroacoustics 2024 in Rome).



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